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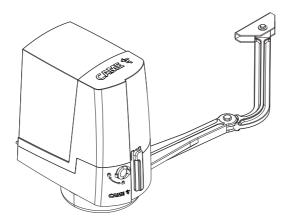
Swing-gate operator

FA00441-EN









FTX20DGC / FTX20DLC

INSTALLATION MANUAL



Fabbricante / Manufacturer / Hersteller / Fabricant / Fabricante / Fabricante / Wytwórca / Fabrikani

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Legale Rappresentante / Legal Representative /Gesetzlicher Vertreter / Representant Legal / Representante Legal / Representante Legal / Prawny Przedstawiciel / Juridische Vertegenwoordigei

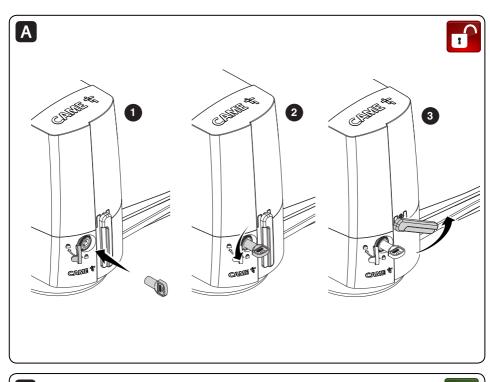
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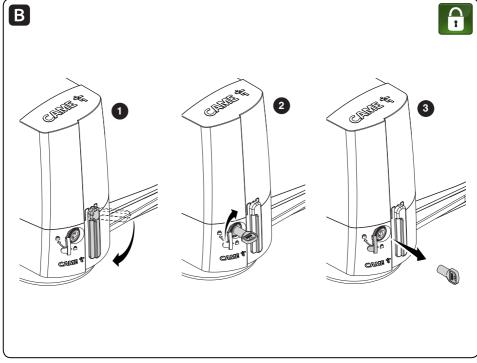
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△ WHEN CLEANING, MAINTAINING AND REPLACING PARTS, DISCONNECT THE OPERATOR FROM THE MAINS POWER SUPPLY (EXCLUDING POINT B)

At least every six months, perform ordinary maintenance jobs.

- △ When performing this procedure, keep clear of the movement of the boom.
- A Wipe clean the photocells' glass with a soft, slightly water-dampened cloth. Do not use any solvents or other chemicals.
- B Check that the photocells are working properly by waving an object between them when the boom is moving: if the boom inverts its direction or the maneuver is stopped, the photocells are working properly.
- C Check that there are no impediments to the proper operation of the operator, such as any overgrown vegetation that could block the photocells or any changes or yielding to the barrier's structure.

Any repairs, or changes to the installation must be performed by qualified staff and all jobs logged carefully.

WHAT TO DO IF ...

ISSUES	POSSIBLE CAUSES	POSSIBLE FIXES
The operator neither opens nor closes	 Power supply is missing The gearmotor is stuck The transmitter emits a weak signal or no signal Release lever is raised 	 Check main power supply Lock the gearmotor Replace the batteries Make sure the release lever is lowered
	Button/s and/or selectors stuck	Check that the devices and the electric cables are in proper working conditions
The operator opens but does not close	The photocells are working	Check that there are no obstructions in the range of operation of the photocells

 \triangle If the problem cannot be solved by following the fixes in the table or if any malfunctions, anomalies, noises, vibrations or suspicious and unexpected behavior is experienced on the system, call for qualified assistance.

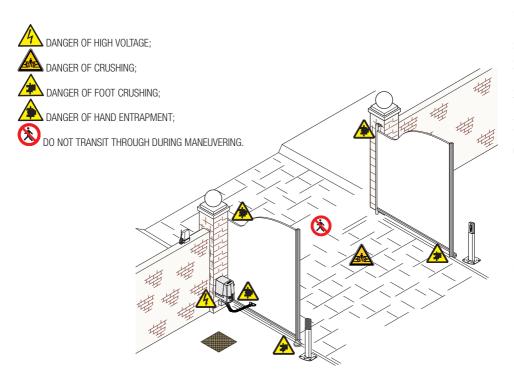
A CAUTION! Important safety instructions. Follow all of these instructions. Improper installation can cause serious bodily harm.

Before continuing, also read the general precautions for users.

This product must only be used for its specifically intended purpose. Any other use is dangerous. CAME S.P.A. IS NOT LIABLE FOR ANY DAMAGE CAUSED BY IMPROPER, WRONGFUL AND UNREASONABLE USE. • THIS MANUAL'S PRODUCT IS DEFINED BY MACHINERY DIRECTIVE 2006/42/CE AS "PARTLY-COMPLETED MACHINERY". PARTLY-COMPLETED MACHINERY IS A SET THAT ALMOST CONSTITUTES A MACHINE, BUT WHICH, ALONE, CANNOT ENSURE A CLEARLY DEFINED APPLICATION. PARTLY-COMPLETED MACHINERY IS ONLY DESTINED TO BE INCORPORATED OR ASSEMBLED TO OTHER MACHINERY OR OTHER PARTLY-COMPLETED MACHINERY OR APPARATUSES TO BUILD MACHINERY THAT IS REGULATED BY DIRECTIVE 2006/42/CE. THE FINAL INSTALLATION MUST BE COMPLIANT WITH EUROPEAN DIRECTIVE 2006/42/CE AND EUROPEAN REFERENCE STANDARDS: EN 13241-1, EN 12453, EN 12445 ED EN 12635. • GIVEN THESE CONSIDERATIONS, ALL PROCEDURES STATED IN THIS MANUAL MUST BE EXCLUSIVELY PERFORMED BY EXPERT, QUALIFIED STAFF. • LAYING THE CABLES, INSTALLATION AND TESTING MUST FOLLOW STATE-OF-THE-ART PROCEDURES AS DICTATED BY REGULATIONS BEFORE INSTALLING THE OPERATOR, CHECK THAT THE GATE IS IN PROPER MECHANICAL CONDITION, THAT IT IS PROPERLY BALANCED AND THAT IT PROPERLY CLOSES: IF ANY OF THESE CONDITIONS ARE NOT MET, DO NOT CONTINUE BEFORE HAVING MET ALL SAFETY REQUIREMENTS. • THE OPERATOR CANNOT BE USED WITH GATES FITTED WITH PEDESTRIAN DOORS, UNLESS ITS OPERATION CAN BE ACTIVATED ONLY WHEN THE PEDESTRIAN DOOR IS IN SAFETY POSITION. • Make sure that people cannot bet entrapped between the gate's moving and fixed parts due to THE GATE'S MOVEMENT. • DO NOT FIT THE OPERATOR UPSIDE DOWN OR ONTO ELEMENTS THAT COULD YIELD TO ITS WEIGHT. IF NECESSARY, ADD REINFORCEMENTS TO THE FASTENING POINTS ● CHECK THAT THE TEMPERATURE RANGE APPEARING ON THE OPERATOR IS SUITED TO THE PLACE OF INSTALLATION ● DO NOT INSTALL DOOR OR GATE LEAVES ON TILTED SURFACES ● CHECK THAT NO LAWN WATERING DEVICES SPRAY THE OPERATOR WITH WATER FROM THE BOTTOM UP ● SUITABLY SECTION OFF AND DEMARCATE THE ENTIRE INSTALLATION SITE TO PREVENT UNAUTHORIZED PERSONS FROM ENTERING THE AREA, ESPECIALLY MINORS AND CHILDREN. • USE PROPER PROTECTIONS TO PREVENT MECHANICAL HAZARDS WHEN PEOPLE ARE LOITERING AROUND THE MACHINERY'S RANGE OF ACTION, FOR EXAMPLE, PREVENT CRUSHING OF FINGERS BETWEEN THE DRIVE SHAFT AND THE MECHANICAL STOPS, PREVENT CRUSHING WHEN THE GATE IS OPENING, AND SO ON. • ANY RESIDUAL RISKS MUST BE INDICATED CLEARLY WITH PROPER SIGNAGE AFFIXED IN VISIBLE AREAS. ALL OF WHICH MUST BE EXPLAINED TO END USERS. AFFIX CAUTIONARY SIGNS, SUCH AS THE GATE PLATE, WHEREVER NEEDED AND IN PLAIN SIGHT THE GATE PLATE, WHEREVER NEEDED AND IN PLAIN SIGHT, • ALL OPENING CONTROLS MUST BE INSTALLED AT LEAST 1.85 M FROM THE PERIMETER OF THE GATE'S WORKING AREA. OR WHERE THEY CANNOT BE REACHED FROM OUTSIDE THE GATE. • If the operator is installed lower than 2.5 from the ground or from any other access level. FIT ANY PROTECTIONS AND SIGNS TO PREVENT HAZARDOUS SITUATIONS. • MAKE SURE THAT MECHANICAL STOPS ARE ALREADY INSTALLED. MAKE SURE THE OPERATOR IS INSTALLED ONTO A STURDY SURFACE THAT IS PROTECTED. FROM ANY COLLISIONS • UNLESS THE KEY-OPERATION IS FUNCTIONING (FOR E.G. KEYPAD SELECTOR, KEY-SWITCH SELECTOR, TRANSPONDER SELECTOR, AND SO ON), ANY MAINTAINED-ACTION CONTROL DEVICES MUST BE INSTALLED AT LEAST 1.5 M FROM THE GROUND AND OUT OF REACH FROM UNAUTHORIZED USERS. ● THE MANUFACTURER DECLINES ANY LIABILITY FOR USING NON-ORIGINAL PRODUCTS; WHICH WOULD RESULT IN WARRANTY LOSS ● ALL SWITCHES IN MAINTAINED ACTION MODE MUST BE POSITIONED SO THAT THE MOVING GATES LEAVES. THE TRANSIT AREAS AND VEHICLE THRU-WAYS ARE COMPLETELY VISIBLE, AND YET THE SWITCHES MUST BE ALSO AWAY FROM

ANY MOVING PARTS • AFFIX A PERMANENT TAG, THAT DESCRIBES HOW TO USE THE MANUAL RELEASE MECHANISM, CLOSE TO THE MECHANISM. • BEFORE HANDING OVER TO USERS, CHECK THAT THE SYSTEM IS COMPLIANT WITH THE 2006/42/CE UNIFORMED MACHINERY DIRECTIVE. Make sure the settings on the operator are all suitable and that any safety and protection devices, and also the manual release, work properly. • If the power-supply cable is damaged, it must be immediately replaced by the manufacturer or by an authorized technical assistance center, or in any case, by qualified staff, to prevent any risk • During all phases of the installation make sure you have cut off the mains power source. • The electrical cables must run through the cable glands and must not touch any heated parts, such as the motor, transformer, and so on). • Make sure you have set up a suitable dual pole cut off device along the power supply that is compliant with the installation rules. It should completely cut off the power supply according to category III surcharge conditions. • Keep the section of this manual inside the technical folder along with the manuals of all the other devices used for your automation system. Remember to hand over to the end users all the operating manuals of the products that make up the final machinery.

THE NEXT FIGURE SHOWS THE MAIN HAZARD POINTS FOR PEOPLE.



KEY

- This symbol shows which parts to read carefully.
- ⚠ This symbol shows which parts describe safety issues
- This symbol shows which parts to tell users about.

The measurements, unless otherwise stated, are in millimeters.

DESCRIPTION

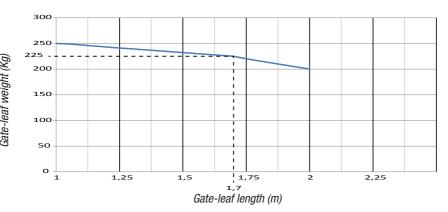
Operator complete with control board, movement control and obstruction detecting device plus mechanical endstops for swing gates with leaves up to 2 m.

INTENDED USE

This operator is designed to power swing gates for residential and apartment block use.

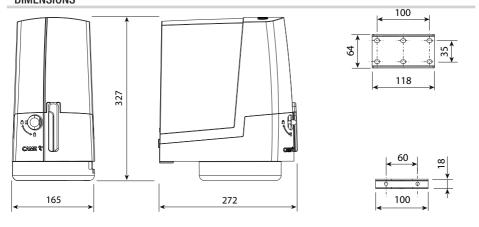
Any installation and/or use other than that specified in this manual is forbidden.

LIMITS TO USE



⚠ We suggest you always fit an electrolock onto swing gates for a more reliable closure.

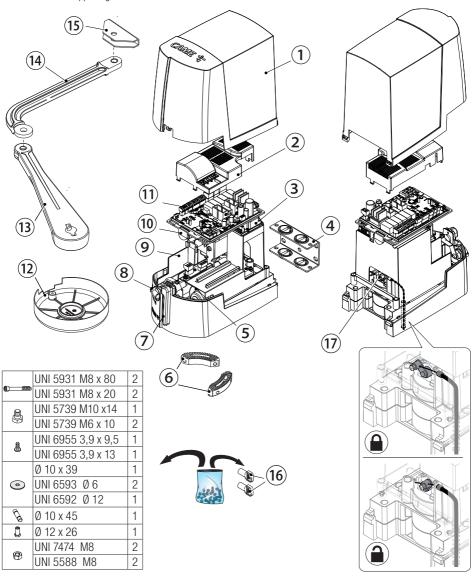
DIMENSIONS



DESCRIPTION OF PARTS

- 1. Cover
- 2. Control-board protective cover
- 3. EMC02 card
- 4. Post brace
- 5. Gearmotor
- 6. Mechanical stops
- 7. Release lever
- 8. Lock
- 9. Control-board supporting structure

- 10. Control-board supporting plate
- 11. ZL65 control board
- 12. Transmission arm protection
- 13. Transmission arm
- 14. Joint arm
- 15. Gate brace
- 16. Release keys
- 17. Release shaft for optional, pull-cord device



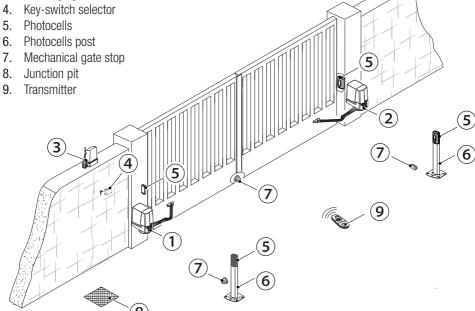
TECHNICAL DATA

Model	FTX20DGC - FTX20DLC
Protection rating (IP)	44
Power supply (V - 50/60 Hz)	230 AC
Input voltage motor (V)	24 DC
Max draw (A)	4
Stand-by consumption (W)	7
Stand-by consumption with the RGP1 (W) module	0.5
Maximum power (W)	140
Cycles/hour	40
Operating temperature (°C)	-20 to +55
Torque (Nm)	180
Opening time at 90° (s)	from 20 to 30
Gear ratio	1/1680
Apparatus class	1
Acoustic pressure dB (A)	≤70
Weight (Kg)	10.5

STANDARD INSTALLATION

- Operator
- Gearmotor
- Flashing light
- 5.
- 7.





GENERAL INSTALLATION INDICATIONS

PRELIMINARY CHECKS

▲ Before beginning the installation, do the following:

- check that the gate structure is sturdy enough, the hinges work efficiently and that there is no friction between the fixed and moving parts;
- if ground stops are not, or cannot be, fitted, use the supplied mechanical stops;
- make sure that the point where the gearmotor is fastened is protected from any impacts and that the surface is solid enough;
- set up suitable tubes and conduits for the electric cables to pass through, making sure they are protected from any mechanical damage.

CABLE TYPES AND MINIMUM THICKNESSES

Connection	cable length		
Connection	< 20 m	20 < 30 m	
Input voltage for 230 V AC control board (1P+N+PE)	3G x 1.5 mm ²	3G x 2.5 mm ²	
24 V DC gearmotor	3 x 1.5 mm ²	3 x 2.5 mm ²	
Electric lock	2 x 0.5	5 mm ²	
Flashing light	2 x 0.5 mm ²		
Command and control devices	2 x 0.5	i mm²	
TX Photocells	2 x 0.5 mm ²		
RX photocells	4 x 0.5	5 mm ²	

When operating at 230 V and outdoors, use H05RN-F-type cables that are 60245 IEC 57 (IEC) compliant;
whereas indoors, use H05VV-F-type cables that are 60227 IEC 53 (IEC) compliant. For power supplies up to
48 V, you can use FROR 20-22 II-type cables that comply with EN 50267-2-1 (CEI).

- To connect the antenna, use the RG58 (we suggest up to 5 m).
- For paired connection and CRP, use a UTP CAT5-type cable (up to 1,000 m long).
- ☐ If cable lengths differ from those specified in the table, establish the cable sections depending on the actual power draw of the connected devices and according to the provisions of regulation CEI EN 60204-1.
- For multiple, sequential loads along the same line, the dimensions on the table need to be recalculated according to the actual power draw and distances. For connecting products that are not contemplated in this manual, see the literature accompanying said products

INSTALLATION

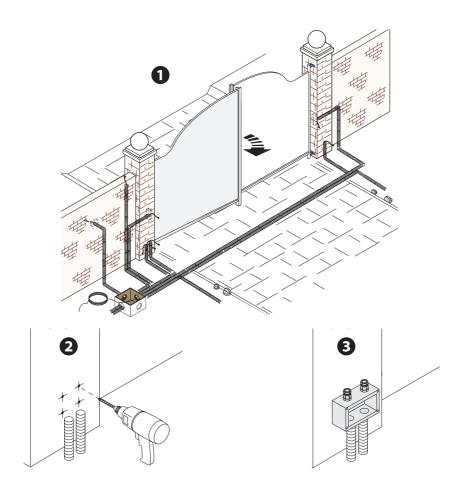
△The following illustrations are mere examples in that the space for fastening the operator and accessories varies depending on the installation area. It is up to the fitter, therefore, to choose the most suitable solution.

The following figures show a standard installation with the gearmotor and transmission arms fitted to the left of the inward-opening gate. Fitting the gearmotor with the transmission arms to the right is done symmetrically. Careful! For outward opening gate leaves, follow the chapter titled "INSTALLING AND CONNECTING FOR OUTWARD OPENING".

INITIAL WORKS

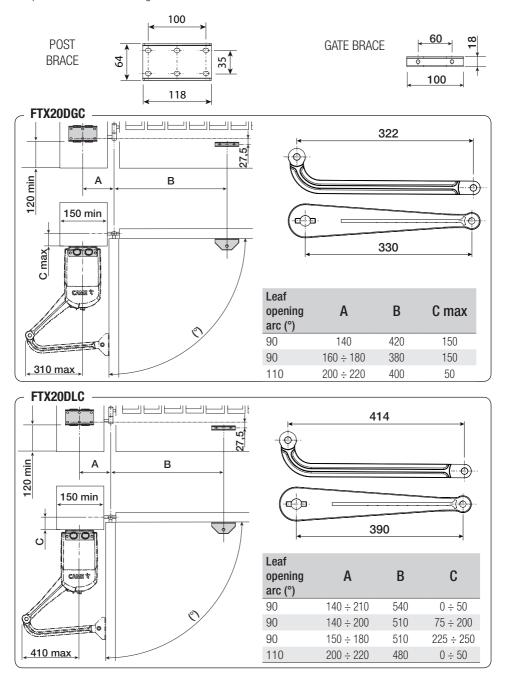
Fit junction boxes and corrugated tubing needed for the incoming connections from the distribution pit.

The number of tubes depends on the type of system and the accessories you are going to fit. You will need at least two corrugated tubes where the operator is installed (on the gate leaf that opens first).



CHECKING MEASUREMENTS AND APPLICATIVE DIMENSIONS

Establish where you will fit the gate brace and measure where the gate-post brace will fit. Make sure to respect the quotas shown in the drawing and table.



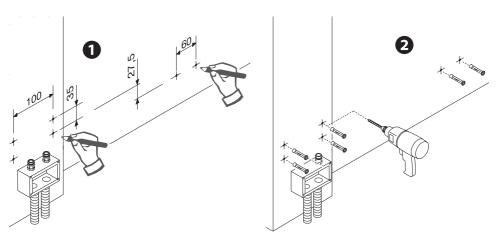
FASTENING THE BRACES

Marked the spots where the gate-post brace and gate brace will be fitted.

The fastening measurements are listed in the paragraph titled CHECKING MEASUREMENTS AND APPLICATIVE DIMENSIONS.

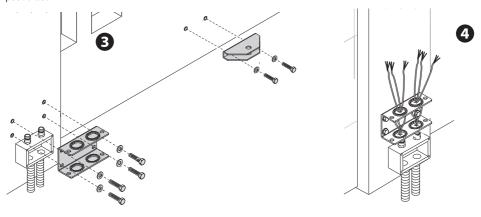
Drill the anchoring points, fit the dowels or use plugs that will hold fast the screws.

The drawings are mere examples. Installers should carefully choose the most suitable set up according to the type and thickness of the gate leaf.



Use suitable screws to fasten the brackets.

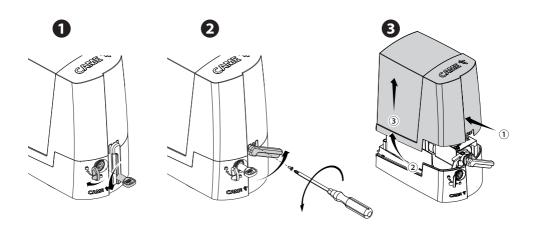
△ Lay the necessary electrical cables and run them through the cable gland and lock them to the clamp of the post brace.



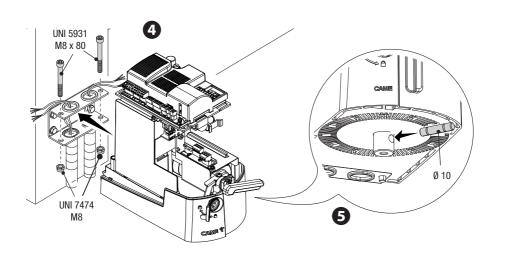
PREPARING AND FASTENING THE OPERATOR

Remove the operator's cover in the following way: - open the lock protection cap, fit, the trilobe key into the lock and turn in counter-clockwise;

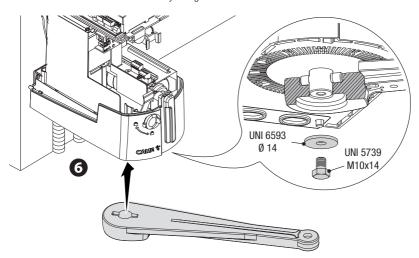
- turn the release lever and loosen the screw that fastens the cover to the gearmotor;
- push the cover back and lightly pull on its sides to lift it.



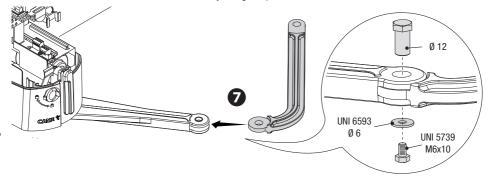
Fit the gearmotor into the gate-post brace and tighten the nuts and bolts. Fit the plug into the socket on the gearmotor drive-shaft.



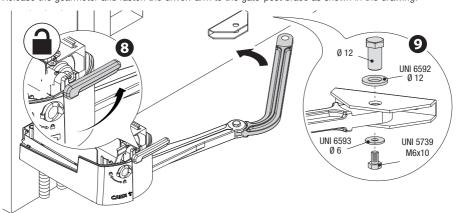
Fit the transmission arm to the shaft by using the slow-shaft washer and the bolt.



Fasten the driven-arm to the transmission arm by using the pin, the bolt and the washer.



Release the gearmotor and fasten the driven-arm to the gate-post brace as shown in the drawing.

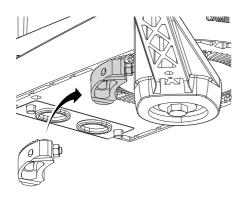


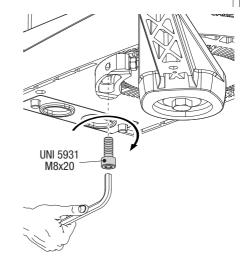
Release the gearmotor.

When opening.

Entirely open the gate leaf. Fit the stop under the casing, against the transmission arm and fasten it with the bolt.



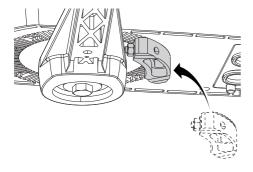


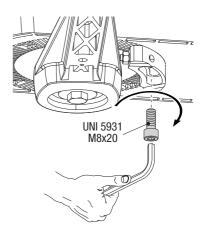


When closing.

Close the leaf. Fit the second stop against the opposite side of the arm and fasten it with the bolt.

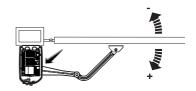


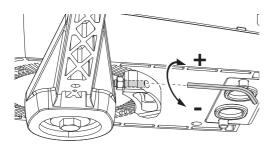


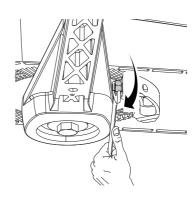


ESTABLISHING THE LIMIT-SWITCH POINTS

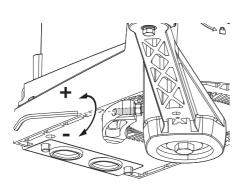
With the gearmotor released and the gate-leaf closed, adjust the closing limit-switch grub screw by turning it clockwise or counterclockwise. Tighten the nut to fasten the grub-screw.

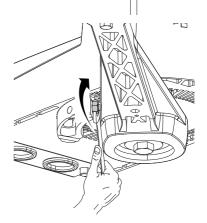






Likewise, adjust the endstop by turning the endless screw on the other endstop. $\ensuremath{\mathsf{e}}$





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IIII

CONTROL CARD

△Warning! Before working on the control panel, cut off the main power supply and, if present, remove any batteries.

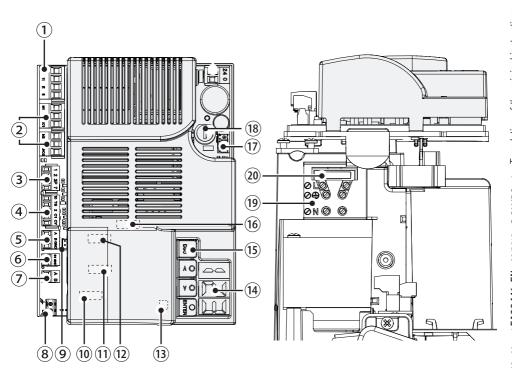
All wiring connections are quick-fuse protected.

Fuses	ZL65
LINE - Line	2 A-F = 230 V
ACCESSORIES - Accessories	2 A-F

DESCRIPTION OF PARTS

- 1. Terminals for signaling devices
- 2. Gearmotors with encoder terminals
- 3. Control devices terminals
- 4. Safety devices terminals
- 5. CRP connection terminals
- 6. Terminals for transponder devices
- 7. Keypad selector terminal
- 8. Antenna terminal
- 9. Module connector CONNECT GW
- 10. AF card connector

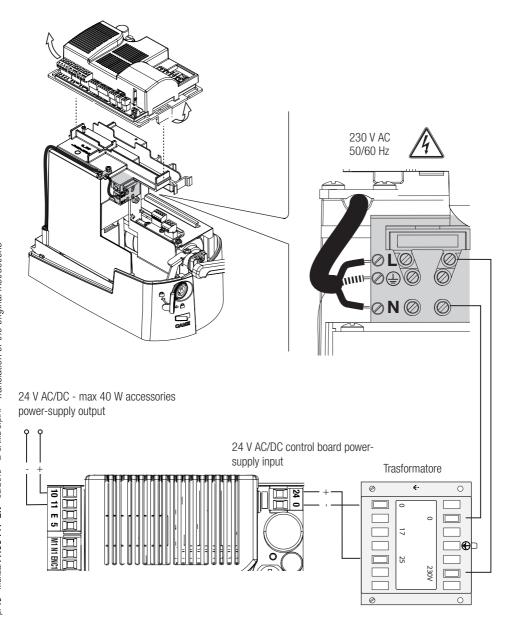
- 11. R700/R800 board connector
- 12. Connector for the RIO-CONN card
- 13. Memory Roll card connector
- 14. Display
- 15. Programming buttons
- 16. RSE board connector
- 17. Terminals for the RGP1 module
- 18. Accessories fuse
- 19. Power supply terminal board
- 20. Line fuse



ELECTRICAL CONNECTIONS

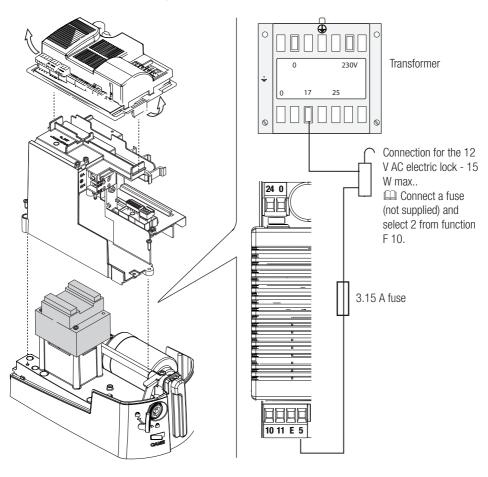
⚠ The electrical cables must not touch any heated parts such as the motor, transformer, and so on.

POWER SUPPLY

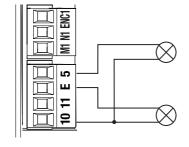


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WARNING! An electric lock must be fitted to gate leaves exceeding 2.5 m in length when using irreversible gearmotors. Electric locks must always be fitted when using reversible gearmotors. Connect the electric lock to the transformer's 17 V output and to terminal 5 on the control board. WARNING! To access the transformer, you will need to remove the control board brace.



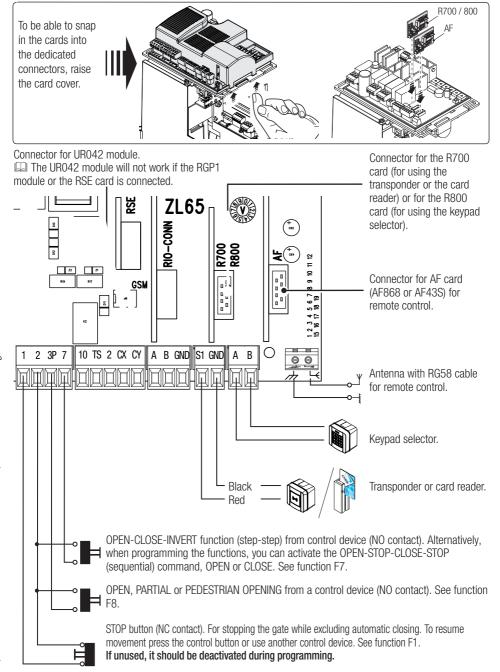
SIGNALING DEVICES

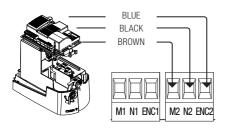


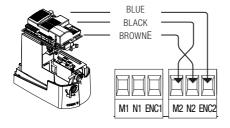
Gate open signaling output (Contact rated for: 24 V AC/DC - 3 W max.). See function F 10.

Either flashing light or cycle light connection output (Contact rated for: 24 V AC/DC - 25 W max.). See function F 18.

WARNING! For the system to work properly, before fitting any plug-in card, such as the AF or R800 one, you MUST CUT OFF THE MAINS POWER SUPPLY and, if present, disconnect any batteries.







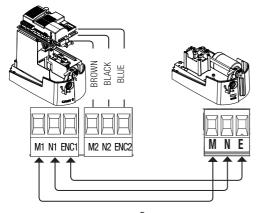
Operator installed on the left (outer view). (**Default setting**)



Operator installed on the right (inner view).

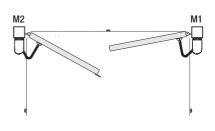


OPERATOR WITH GEARMOTOR

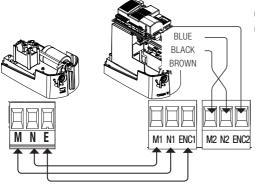


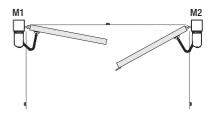
Operator installed on the left and gearmotor installed on the right (inner view) with operator delayed when closing.

(Default setting)



Operator fitted to the right and gearmotor to the left (inner view) with operator delayed when opening.

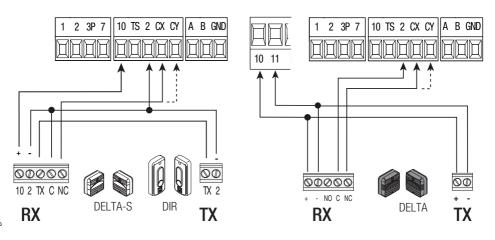




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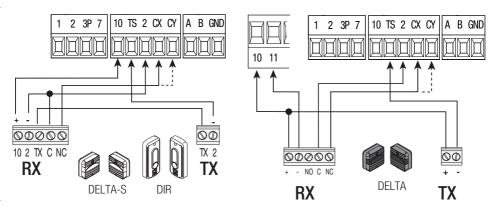
Configure contact CX or CY (NC), safety input for photocells. See CX input functions (Function F2) or CY (Function F3) in:

- C1 reopening during closing. When the gate is closing, opening the contact triggers the inversion of movement until the gate is fully open again;
- C2 close back up during opening. When the gate is opening, opening the contact triggers the inversion of movement until the gate is completely closed.
- C3 partial stop. Opening the contact triggers the gate to stop, if it is moving, and to shift into automatic closing (if the automatic closing function has been set):
- C4 obstruction wait. Opening the contact triggers the gate to stop, if it is moving, and to resume its movement once the obstruction is removed.
- lf contacts CX and CY are not used they should be deactivated during programming.



Photocells (safety test)

Upon each opening and closing command, the board checks the efficiency of the photocells. Any malfunction will inhibit any command and E 4 will appear on the display. For this type of connection, enable function F 5.

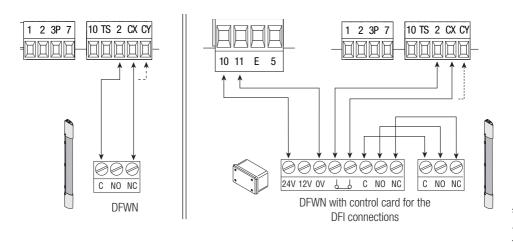


Sensitive Safety Edges

Configure contact CX or CY (NC), input for safety devices, such as sensitive safety edges, that comply with EN 12978 provisions.

See CX input functions (Function F2) or CY (Function F3) in:

- C7 reopening during closing. When the gate is closing, opening the contact triggers the inversion of movement until the gate is fully open again;
- C8 reclosing during opening. When the gate is opening, opening the contact triggers the inversion of movement until the gate is fully closed.
- If contacts CX and CY are not used they should be deactivated during programming.



WIRELESS DEVICES

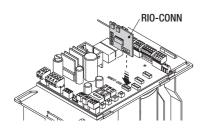
Fit the RIO-CONN card into the corresponding connector on the control board.

Set the function which is to be associated with the wireless device (F 65, F66, F 67 and F 68).

Configure the wireless accessories (see the folder of the accessory you want to configure).

If the devices are not configured with the RIO-CONN card, the E 18 error message is displayed.

⚠ If the system has radiofrequency interferences, the wireless system will inhibit the operator's normal operating mode and the E 17 error message is displayed.



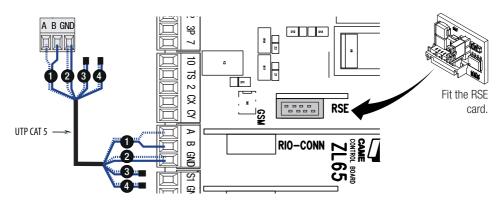






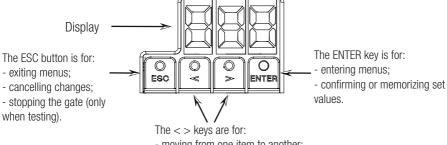
CONNECTION WITH CAME REMOTE PROTOCOL (CRP)

RS485 serial connection with RSE card via CRP (Came Remote Protocol).

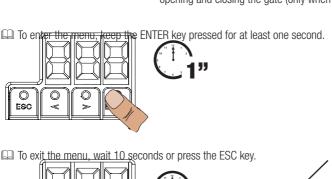


PROGRAMMING

DESCRIPTION OF THE PROGRAMMING COMMANDS



- moving from one item to another;
- increasing or decreasing a value;
- opening and closing the gate (only when testing).





ESC

F1	Total stop [1-2]	NC input – Gate stop that excludes any automatic closing; to resume movement, use the control device. The safety device should be fitted into 1-2. If unused, select OFF. OFF (default) / ON
F2	Input [2-CX]	NC input – Can associate: C1 = reopening during closing by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges (with clean contact), C8 = reclosing during opening by sensitive safety-edges (with clean contact). The C3 Partial stop function only appears if the F 19 Automatic closing time function is activated.
		OFF (default) / C1 / C2 / C3 / C4 / C7 / C8
F3	Input [2-CY]	NC input – Can associate: C1 = reopening during closing by photocells, C2 = reclosing during opening by photocells, C3 = partial stop, C4 = obstruction wait, C7 = reopening during closing by sensitive safety-edges (with clean contact), C8 = reclosing during opening by sensitive safety-edges (with clean contact). The C3 Partial stop function only appears if the F 19 Automatic closing
		time function is activated.
		OFF (default) / C1 / C2 / C3 / C4 / C7 / C8
F5	Safety test	After every opening or closing command, the board will check whether the photocells are working properly. The safety test is always active for wireless devices.
		OFF (default) $/ 1 = CX / 2 = CY / 4 = CX + CY$
F6	Maintained action	The gate opens and closes by keeping the button pressed. Opening button on contact 2-3P and closing button on contact 2-7. All other control devices, even radio-based ones, are excluded.
		OFF (default) / ON
F7	Command [2-7]	From the control device connected to 2-7 it performs the step-step (open-close-invert) or sequential (open-stop-close-stop) command.
		0 = Step-step (default) / $1 = Sequential / 2 = Open / 3 = Close$
F8	Command [2-3P]	From the control device connected to 2-3P it executes the pedestrian opening (completely opens the M2 gate leaf) or partial opening (it partially opens the M2 gate leaf: the opening arc depends on the percentage of travel set up with F36).
		0 = Pedestrian opening (default) / 1 = Partial opening / 2 = Open
F9	Obstruction detection with motor stopped	With the gate closed, opened or totally stopped, the gearmotor stays idle if the safety devices, that is, photocells or sensitive safety-edges detect an obstruction.
		OFF (default) / ON

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F10	Output for gate open or for enabling the electric lock	It signals the gate status. The signaling device is connected to 10-5 or, alternatively, it enables the electric lock connected to the 17 V output of the transformer and to terminal 5. $0 = 0n$ when the barrier is open and moving (default) / $1 = during$ openings it flashes intermittently each half second, and during closings it flashes intermittently each second. It stays on steadily when the barrier is open, off or when it s closed $/2 = electric lock$ is enabled
F11	Encoder	Managing slow-downs, obstruction detections and sensitivity. With this function deactivated, adjust the working time of function F22, in this way, the gearmotor perform maneuvers at slower speeds. OFF / ON (default)
F12	Soft Start	With each opening and closing command, the gate starts moving slowly for a few seconds. OFF (default) / ON
F13	Closing thrust	At the closing limit switch, the gearmotors make the leaves perform a brief closing thrust. OFF (default) // 1 = minimum thrust / 2 = medium thrust / 3
F14	Sensor type	Setting the type of accessory for controlling the operator. 0 = command with transponder sensor or magnetic card reader / 1 = command with keypad selector (default)
F16	Stop Jolt	Before every opening or closing maneuver, the leaves thrust inwards to release the electric lock. The thrust time, is set with F 26. OFF (default) / ON
F18	Additional light	Output for connecting the additional light onto 10-E. Flashing light: it flashes when the gate is opening and closing. Cycle light: additional external light for increasing illumination in the drive way. It stays on from the moment the leaf starts opening until it again closes completely - including the waiting time before the automatic-closing time.
F19	Automatic Closing Time	O = Flashing light (default) / 1 = Cycle The automatic-closing wait starts when the opening limit switch point is reached and can be set to between 1 and 180 seconds. The automatic closing does not activate if any of the safety devices trigger when an obstruction is detected, or after a total stop, or during a power outage.
		OFF (default) / 1 = 1 second / / 180 = 180 seconds
F20	Automatic closing time after pedestrian or partial openings	The wait before the automatic closing starts after a partial opening command for an adjustable time of between 1 s and 180 s. The automatic closing does not activate if any of the safety devices trigger when an obstruction is detected, or after a total stop, or during a power outage. OFF (default) $/ 1 = 1 \ second / / 180 = 180 \ seconds$
F21	Pre-flashing time	Adjusting the pre-flashing time for the flashing light connected to 10-E before each maneuver. The flashing time is adjustable from one to ten seconds.
F22	Operating time	OFF (default) / $1 = 1$ second / / $10 = 10$ seconds Motors working time, when opening and closing. Adjustable between five and 180 seconds. $5 = 5$ seconds / / $120 = 120$ seconds (default) / / $180 = 180$ seconds

F23	Delay in opening time	is settable between one and ten seconds.
	, ,	0 = Deactivated // 2 = 2 seconds (default) // 10 = 10 seconds
F24	Closing delay time	After either a closing command or an automatic closing, the M2 gearmotor starts delayed. The delay time is adjustable between 1 and 25 seconds.
		0 = Deactivated // 5 = 5 seconds (default) // 25 = 25 seconds
F26	Closing thrust time	After an opening or closing command, the gearmotor thrusts inward for an adjustable time between one and two seconds.
		1 = 1 second (default) $/ 2 = 2$ seconds After an opening or closing command, the electric lock releases for an
F27	Lock time	adjustable time between one and four seconds.
		1 = 1 second (default) // 4 = 4 seconds
500		Setting the gate's opening and closing speeds, calculated as a percentage.
F28	Gate travel speed	60 = 60% of the maximum speed $//$ 100 = 100% of the maximum speed (default)
		Setting the gate's opening and closing slow-down speed, calculated as a percentage.
F30	Slow-down speed	10 = 10% of the maximum speed // 50 = 50% of the maximum speed (default) // 60 = 60% of the maximum speed
F33	Calibration speed	Setting the gearmotors' speeds during calibration, calculated as a percentage. $20 = 20\%$ of the maximum speed / / $50 = 50\%$ of the maximum speed (default) // $60 = 60\%$ of the maximum speed
F34	Travel sensitivity	Adjusting obstruction detection sensitivity during gate travel.
104	navor sonsitivity	10 = Maximum sensitivity / / 100 = Minimum sensitivity (default)
F35	Slow-down sensitivity	Adjusting obstruction detection sensitivity during slow-down.
. 00	olon donn conclusity	10 = Maximum sensitivity / / 100 = Minimum sensitivity (default)
	Adjusting the partial	Adjustment as a percentage of total travel, during gate opening.
F36	opening	10 = 10% of the gate travel // $40 = 40%$ of the gate travel (default) / / $80 = 80%$ of the gate travel
F37	Opening slow-down point for the M1 motor	Adjustment as a percentage of total travel, of the beginning slow-down point of gearmotor M1 during opening. This function only appears if the Encoder function is activated. 1 = 1% of the gate travel // 25 = 25% of the gate travel (default) // 60 = 60% of the gate travel
		Adjustment as a percentage of total travel, of the beginning slow-down point
F38 Closing slow-down		of gearmotor M1 during closing. This function only appears if the Encoder function is activated.
. 50	point of the M1 motor	1 = 1% of the gate travel // $25 = 25%$ of the gate travel (default) // $60 = 60%$ of the gate travel
		Adjusting as a percentage of the total travel, the M1 motor's opening
F39	Opening approach point of the M1 motor	approach starting point. This function only appears if the Encoder function is activated.
		1 = 1% of the gate travel // $10 = 10%$ of the gate travel (default)

After an opening command, the M1 gearmotor starts delayed. The delay time

F40	Closing approach point for motor M1	Adjusting as a percentage of the total travel, the M1 motor's closing-approach starting point. \square This function only appears if the Encoder function is activated. $1 = 1\%$ of the gate travel // $10 = 10\%$ of the gate travel (default)
F41	Opening slow-down point for motor M2	Adjusting as a percentage of the total travel, the M2 motor's opening slow-down starting point. This function only appears if the Encoder function is activated. $1 = 1\%$ of the gate travel // $25 = 25\%$ of the gate travel (default) // $60 = 60\%$ of the gate travel
F42	Closing slow-down point for motor M2	Adjusting as a percentage of the total travel, the M2 motor's closing slow-down starting point. This function only appears if the Encoder function is activated. $1 = 1\%$ of the gate travel // $25 = 25\%$ of the gate travel (default) // $60 = 60\%$ of the gate travel
F43	Opening approach point for motor M2	Adjusting as a percentage of the total travel, of the M2 motor's opening approach starting point. This function only appears if the Encoder function is activated.
F44	Closing approach point for motor M2	1 = 1% of the gate travel // 10 = 10% of the gate travel (default) Adjusting as a percentage of the total travel, the M2 motor's closing approach starting point. This function only appears if the Encoder function is activated. 1 = 1% of the gate travel // 10 = 10% of the gate travel (default)
F46	Number of motors	For setting the number of motors connected to the control panel. $\mathbf{OFF} = M1$ and $M2$ ($\mathbf{default}$) / $\mathbf{ON} = M2$
F49	Managing the serial connection	For enabling the CRP (Came Remote Protocol). $OFF / 3 = CRP (default)$
F50	Saving data	Saving users and saved settings in memory roll. This function only appears if a memory roll has been fitted into the control board. OFF (default) / ON
F51	Reading of data	Uploading data saved in memory roll. This function only appears if a memory roll has been fitted into the control board. OFF (default) / ON
F56	Peripheral number	To set the peripheral's number from 1 to 255 for each control board when you have a system with several operators. 1> 255
F63	COM speed	For setting the communication speed used in the CRP (Came Remote Protocol) connection system. 0 = 1200 Baud / 1 = 2400 Baud / 2 = 4800 Baud / 3 = 9600 Baud / 4 = 14400 Baud / 5 = 19200 Baud / 6 = 38400 Baud (default) / 7 = 57600 Baud / 8 = 115200 Baud

A1	Motor type	For setting the type of gearmotor fitted onto the system. 1 = SWN20 - SWN25 (default) $/ 2 = FA7024CB / 3 = FTX20DGC$
U4	Decoding the code	Select the type of transmitter radio coding that you wish to save on the control board. A When you select a radio coding, all saved transmitter are automatically deleted. The TWIN coding lets you save multiple user with the same key (Key block). 1 = all (default) / 2 = Rolling Code / 3 = TWIN
U3	Deleting users	Deleting all users. OFF / ON = Delete all users
U2	Deleting users	Deleting a single user OFF / ON = Enabling the deletion of single users.
U1	Entering users	Entering up to 250 users and associating to each one a function of choice among those included. Add users via a transmitter or other control device (see the paragraph called ADDING USERS WITH AN ASSOCIATED COMMAND). 1 = Step-step command (open-close) / 2 = Sequential command (open-stop-close-stop) / 3 = Only open command / 4 = Partial command
F68	Wireless input RIO-CELL [T2]	RIO-CELL is associated to any function chosen among those available: P1 = reopening during closing; P2 = reclosing during opening; P3 = partial stop; P4 = obstruction wait. For programming, see the instructions that come with the accessory. This function only appears is the control board has been fitted with a RIO-CONN card. OFF (default) / P1 / P2 / P3 / P4
F67	Wireless input RIO-CELL [T1]	RIO-CELL is associated to any function chosen among those available: P1 = reopening during closing; P2 = reclosing during opening; P3 = partial stop; P4 = obstruction wait. For programming, see the instructions that come with the accessory. This function only appears is the control board has been fitted with a RIO-CONN card. OFF (default) / P1 / P2 / P3 / P4
F66	Wireless input RIO-EDGE [T2]	Wireless (RIO-EDGE) safety device associated to a function chosen among those available: P0 = TOTAL STOP, P7 = reopening during closing, P8 = reclosing during opening. For programming, see the instructions that come with the accessory. This function only appears is the control board has been fitted with a RIO-CONN card. OFF (default) / P0 / P7 / P8
F65	Wireless input RIO-EDGE [T1]	Wireless (RIO-EDGE) safety device associated to a function chosen among those available: P0 = TOTAL STOP, P7 = reopening during closing, P8 = reclosing during opening. For programming, see the instructions that come with the accessory. This function only appears is the control board has been fitted with a RIO-CONN card. OFF (default) / P0 / P7 / P8

A2	Motors test	Test for checking the gearmotors' proper rotating directions (see the MOTORS TEST paragraph). $ \textit{OFF} / \textit{ON} $
A3	Travel calibration	Calibrating the gate travel (see the paragraph called CALIBRATING THE GATE TRAVEL). This function appears only is the Encoder function is activated.
A4	Resetting parameters	OFF / ON Attention! The default settings will be restored.
		OFF / ON For viewing the number of maneuvers completed or for deleting them (001 =
A5 Maneuver count	Maneuver count	100 maneuvers; 010 = 1,000 maneuvers; 100 = 10,000 maneuvers; 999 = 99,900 maneuvers; CSI = maintenance job)
H1	Version	View the firmware version.

SETTING UP

Once the electrical connections are complete, have skilled staff commission the operator.

Before continuing, make sure the area is free of any obstructions, and that there are mechanical, opening and closing gate stops in place.

Power up and begin configuring the system. **Important!** Start programming by first doing the following functions:

- type of motor (A1);
- number of motors (F46);
- motors test (A2), see the specific paragraph;
- travel calibration (A3), see the specific paragraph.

Once the programming is done, verify that the operator and all the accessories are working properly. Use the < > keys to open and close the gate, and the ESC key to stop it.

- After powering up the system, the first maneuver is always the opening. In this phase, the gate cannot be closed. You will need to wait for the gate to completely open.
- △ Immediately press the STOP button if any suspicious malfunctions, noises or vibrations occur in the system.
- Commissioning should be done also after each restoring procedure (A4).

MOTORS TEST

Select A2. Press ENTER to confirm. 1

Select ON. Press ENTER to confirm the motors test procedure. 2

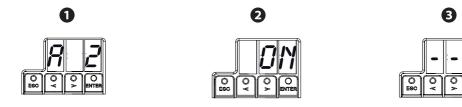
The following [---] characters will be displayed while waiting for a command. 3

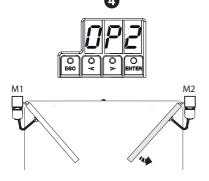
Keep pressed the > key and check whether the M2 second gearmotor's leaf performs an opening maneuver.

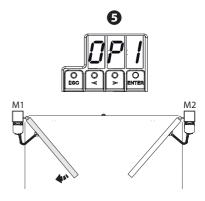
If the leaf performs an opening maneuver, invert the motor's phases.

Perform the same procedure using the < arrow key to check the M1 first gearmotor's leaf.

If the leaf performs an opening maneuver, invert the motor's phases.







TRAVEL CALIBRATION

Before calibrating the gate travel, position the gate half-way, check that the maneuvering area is clear of any obstruction and check that there are mechanical opening and closing stops.

⚠ The mechanical end-stops are obligatory.

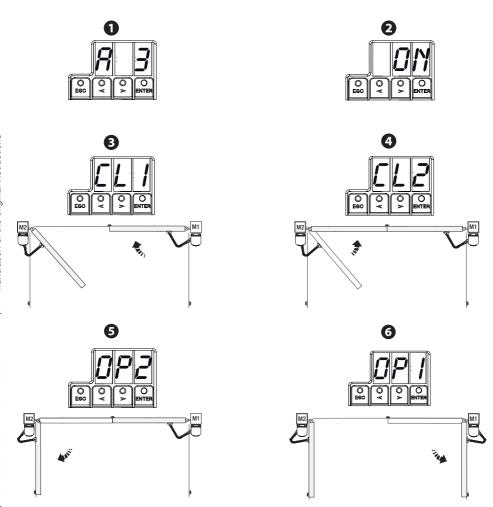
Important! During calibration, all safety devices will be disabled.

Select A3. Press ENTER to confirm.

Select ON. Press ENTER to confirm the automatic travel calibration procedure. 2

The first gearmotor leaf will perform a closing maneuver until the closing strike ... 3

- ... then, the second gearmotor leaf will perform the same maneuver ... 4
- ... the the second gearmotor's leaf will perform an opening maneuver until the closing strike ... §
- ... the first gearmotor's leaf will perform the same maneuver. 6



Before registering the users, make sure the AF radio card is plugged into the connector (see the paragraph called CONTROL DEVICES).

ENTERING A USER WITH AN ASSOCIATED COMMAND

Select U1. Press ENTER to confirm.

Select a command to associate to the user.

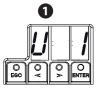
The commands are:

- 1 = step-step (open-close);
- 2 = sequential (open-stop-close-stop);
- -3 = open;
- 4 = partial opening.

Press ENTER to confirm... 2

... a number between 1 and 250 will start flashing for a few seconds.

Send the code from the transmitter or other control device, such as, a keypad selector or a transponder. 3 Note down, the registered users, in the "REGISTERED USERS LIST".







LIST OF REGISTERED USERS

1	11	21	
2	12	22	
3	13	23	
4	14	24	
5	15	25	
6	16	26	
7	17	27	
8	18	28	
9	19	29	
10	20	30	

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127	159	191
128	160	192
129	161	193
130	162	194
131	163	195
132	164	196
133	165	197
134	166	198
135	167	199
136	168	200
137	169	201
138	170	202
139	171	203
140	172	204
141	173	205
142	174	206
143	175	207
144	176	208
145	177	209
146	178	210
147	179	211
148	180	212
149	181	213
150	182	214
151	183	215
152	184	216
153	185	217
154	186	218
155	187	219
156	188	220
157	189	221
158	190	222
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223	233	243	
224	234	244	
225	235	245	
226	236	246	
227	237	247	
228	238	248	
229	239	249	
230	240	250	
231	241		
232	242		

DELETING SINGLE USERS

Select U 2. Press ENTER to confirm. 1

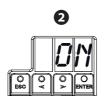
Select ON. Press ENTER to confirm the deletion procedure. 2

Use the arrow keys select the number of the user you wish to delete.

Press ENTER to confirm. 3

... CLr will appear on the screen to confirm deletion. 4









SAVING AND UPLOADING DATA WITH THE MEMORY ROLL

For saving user and system configuration data with the Memory Roll, and for then reusing them on another control board, even on fitted into another system.

WARNING! Fitting and extracting the Memory Roll must be done with the mains power disconnected.

Fit the Memory Roll into the its corresponding connector on the control board. 1

Select F50. Press ENTER to confirm. 2

Select ON. Press ENTER to confirm the data saving procedure. 3

Extract the Memory roll and fit it into the connector of another control board. 4

Select F51. Press ENTER to confirm. **5**

Select ON. Press ENTER to confirm the data uploading procedure. 6

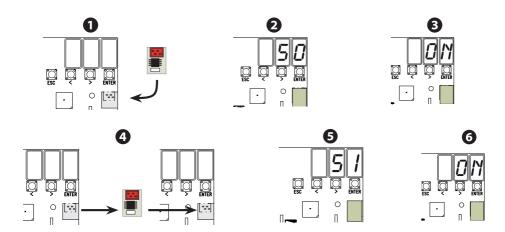
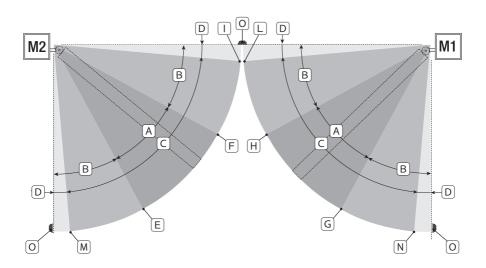


ILLUSTRATION OF THE SLOW-DOWN POINTS AND END-STROKE AREAS

The travel areas and slow-down and approach points are tested to comply with the parameters set forth by Technical Regulations EN 12445 and EN 12453 for impact force compatibility of moving gate leaves.



A = Movement area at normal speed.

 $B^* = Movement$ area at slowed-down speed.

C = Encoder intervention zone with movement inversion.

Encoder intervention zone with movement stopped.

Opening slow-down starting point for M2.

F = Closing slow-down starting point for M2.

G = Opening slow-down starting point for M1.

H = Closing slow-down starting point for M1.

** = Closing approach starting point for M2.

 L^{**} = Closing approach starting point for M1.

 M^{**} = Opening approach starting point for M2.

 N^{**} = Opening approach starting point for M1.

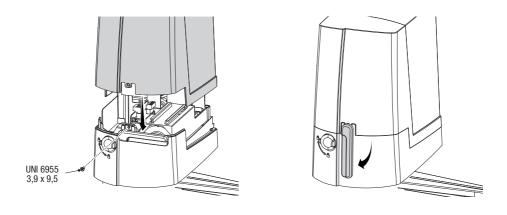
Strike plates..

* Minimum 600 mm from the strike plate.

** Set the closing-rest percentage for function F 39 - F 40 for the first motor (M1) and F43 - F44 for the second motor (M2) so as to achieve a distance of less than 50 mm from the strike plate.

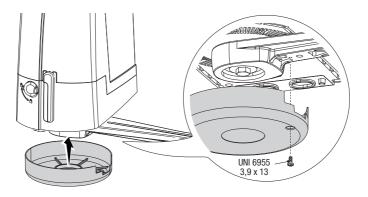
FASTENING THE COVER

Once the electrical connections and set up are done, fit the cover and fasten it using the supplied screws, then reposition the release lever.



FASTENING THE TRANSMISSION ARM PROTECTION

Fit the protection under the operator and fasten it to the transmission arm using the screw.



ERROR MESSAGE

The error messages are shown on the display.

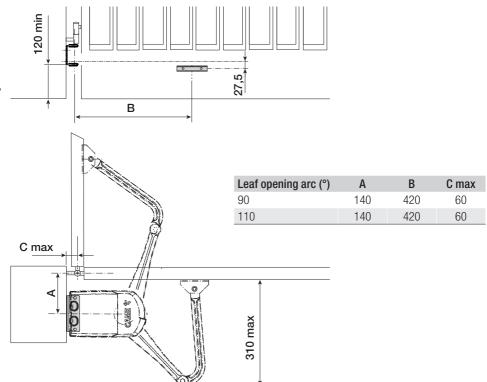
E1	The travel calibration was interrupted when the STOP button was activated
E2	Calibrating the complete gate-travel
E3	Encoder broken
E4	Services test error
E7	Insufficient working time
E9	Closing obstruction
E10	Opening obstruction
E11	Maximum number of detected obstructions
E14	Serial communication error
E15	Incompatible transmitter error
E17	Wireless system error
E18	The wireless system is not configured

INWARD OPENING CONNECTIONS AND INSTALLING

Following, are the only things that change compared to a standard installation:

CHECKING MEASUREMENTS AND APPLICATIVE DIMENSIONS

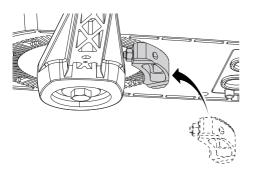
Establish where you will fit the gate brace and measure where the gate-post brace will fit. Make sure to respect the quotas shown in the drawing and table.

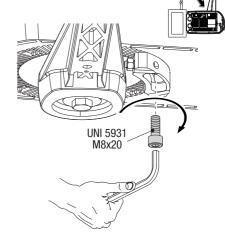


Release the gearmotor.

When opening.

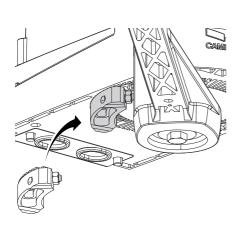
Entirely open the gate leaf. Fit the stop below the casing, against the transmission arm and fasten it by using the bolt.

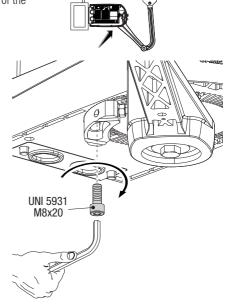




When closing.

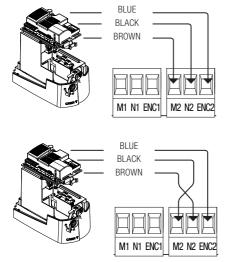
Close the leaf. Fit the second stop against the opposite side of the arm and fasten it with the bolt.





ESTABLISHING THE LIMIT-SWITCH POINTS

Refer to the chapter on opening inwards



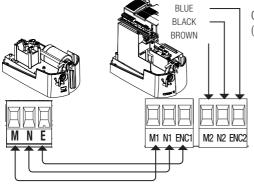
Operator installed on the right (inner view).



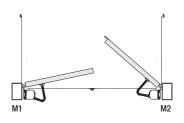
Operator installed on the left (outer view).

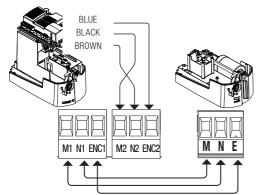


CONNECTING THE OPERATOR AND THE GEARMOTOR

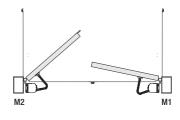


Operator fitted to the right and gearmotor to the left (inner view) with operator delayed when opening.





Operator installed on the left and gearmotor installed on the right (inner view) with operator delayed when closing.



DISMANTLING AND DISPOSAL

©CAME S.p.A. applies a certified Environmental Management System at its premises, which is compliant with the UNI EN ISO 14001 standard to ensure the environment is safeguarded.

Please continue safeguarding the environment. At CAME we consider it one of the fundamentals of our operating and market strategies. Simply follow these brief disposal guidelines:

DISPOSING OF THE PACKAGING

The packaging materials (cardboard, plastic, and so on) should be disposed of as solid household waste, and simply separated from other waste for recycling.

Always make sure you comply with local laws before dismantling and disposing of the product.

DISPOSE OF RESPONSIBLY!

DISMANTLING AND DISPOSAL

Our products are made of various materials. Most of these (aluminum, plastic, iron, electrical cables) are classified as solid household waste. They can be recycled by separating them before dumping at authorized city plants.

Whereas other components (control boards, batteries, transmitters, and so on) may contain hazardous pollutants.

These must therefore be disposed of by authorized, certified professional services.

Before disposing, it is always advisable to check with the specific laws that apply in your area.

DISPOSE OF RESPONSIBLY!



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